## Parallel Line Centers with Guaranteed Separation

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#### Facility-location problems





#### **Facility-location problems**







#### *k*-line-center problem











*k*-**parallel**-line-center problem



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For a given point set *P*,





Given a set of k slabs,

#### k-slab





Given a set of k slabs,

Given a set P of points,

k-slab



k-slab cover of P



*k*-slab  $S = (\sigma_1, ..., \sigma_k)$  when k = 5 $\sigma_1$  $\sigma_2$  $\sigma_3$  $\sigma_4$  $\sigma_5$ 







k-slab S =  $(\sigma_1, \dots, \sigma_k)$  when k = 5 $\sigma_1$  $\sigma_2$  $\sigma_3$  $_{W}(S)$  $\sigma_4$  $\sigma_5$ 

The  $\underline{width}$  of S

• 
$$\mathbf{w}(\mathbf{S}) := \max\{\mathbf{w}(\sigma_1), \mathbf{w}(\sigma_2), ...\}$$



k-slab S =  $(\sigma_1, \dots, \sigma_k)$  when k = 5



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•  $\mathbf{w}(\mathsf{S}) := \max\{\mathbf{w}(\sigma_1), \mathbf{w}(\sigma_2), ...\}$ 

The gap-width of S

•  $g(\mathsf{S}) := \min\{\mathsf{w}(\gamma_1), \mathsf{w}(\gamma_2), ...\}$ 



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The <u>breadth</u> of S

• *b*(S)



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#### The <u>gap-width</u> of S

•  $g(S) := \min\{w(\gamma_1), w(\gamma_2), ...\}$ 

#### The <u>breadth</u> of S

• *b*(S)

#### The gap-ratio of S

•  $\rho(\mathsf{S}) := g(\mathsf{S})/b(\mathsf{S})$ 



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A **separator** of a *k*-slab S:

a sequence of k - 1 points on a common line each of which lies in its distinct gap.



 $R = (r_1, r_2, r_3)$ It holds that  $r_i \in \gamma_i$  for each i = 1, ..., k - 1.



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A *k*-slab S **respects** the separator R .



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Step 1. An algorithm to compute a minimum-width *k*-slab cover of *P* which **respects** a given separator R in  $O(kn \log n)$  time and O(n) space.

Step 2. An algorithm to compute  $O(\rho^{-k})$  candidate separators.



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Step 1. Given a separator  $R = (r_1, ..., r_{k-1})$ , compute a minimum-width *k*-slab cover of *P* respecting *R*.



#### Each of the function

- $W_1, \ldots, W_k$ ,
- $g_1, \ldots, g_{k-1}$
- b

: piecewise sinusoidal with O(n) breakpoints



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 $\rightarrow$  We can compute **the width**, **gap-width**, **breadth**, and **the gap ratio** for a fixed orientation.















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- A fully dynamic structure CH<sub>i</sub> for each i = 1, ..., k [G. S. Brodal and R. Jacob, 2002]
  - $O(\log n)$  time queries using O(n) space.

$$2k$$
 lists (W<sub>1</sub>,..., W<sub>k</sub>, G<sub>1</sub>,..., G<sub>k-1</sub>, and B)

- k lists: Store functions of  $w_i(\theta)$  for i = 1, ..., k :  $W_1, ..., W_k$
- k lists: Store functions of  $w_i(\theta)$  for i = 1, ..., k :  $vv_1, ..., vv_k$  k 1 lists: Store functions of  $g_i(\theta)$  for i = 1, ..., k 1 :  $G_1, ..., G_{k-1}$ 
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  - k-1 lists: Store functions of  $g_i(\theta)$  for i = 1, ..., k-1 :  $G_1, ..., G_{k-1}$
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- The two extreme points  $q_i^+(\theta)$  and  $q_i^-(\theta)$  for each  $P_i(\theta)$

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: when two or more points of *P* are contained in a boundary line of slab of  $P_i(\theta)$ 

2) Cross event : when a point in *P* lies on  $\ell_i(\theta)$ 

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- Update W<sub>i</sub>
- Update  $G_{i-1}, G_i$
- Update B, if needed

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- The number of events is O(kn)
- It takes  $O(\log n)$  time for each event. [G. S. Brodal and R. Jacob, 2002]



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- $\rightarrow$  Evaluate W<sub>1</sub>, ..., W<sub>k</sub>, G<sub>1</sub>, ..., G<sub>k-1</sub>, and B

: Compute the exact orientation  $\theta$  where the gap-ratio is at least  $\rho$  and the width is minimized.

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Step 1. Given a separator  $R = (r_1, ..., r_{k-1})$ , compute a minimum-width *k*-slab cover of *P* respecting *R*.

**Theorem.** A minimum-width *k*-slab cover of *P* respecting R can be computed in  $O(kn \log n)$  time and O(n) space.



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An  $\epsilon$ -coreset for the directional width of P  $d_{\theta}(K) \ge (1 - \epsilon) d_{\theta}(P)$  for any orientation  $\theta$ . θ Κ



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Let  $K \subset P$  be a  $(\rho/2)$ -coreset for directional width of P.  $\rightarrow K$  of size  $O(1/\rho)$  can be computed in O(n) time.





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**Lemma.** For any *k*-slab cover  $S = (\sigma_1, ..., \sigma_k)$  of *P*, it holds that  $K \cap \sigma_1 \neq \emptyset$  and  $K \cap \sigma_k \neq \emptyset$ .



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**Corollary.** There is an antipodal pair (p, q) of K such that  $p \in \sigma_1$  and  $q \in \sigma_k$ .



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**Lemma.** Each gap of *S* contains at least one point in  $R_{pq}$ 



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 $R_{pq}: \lceil 1/\rho \rceil$  equidistant points on  $\overline{pq}$ 

**Lemma.** Each gap of S contains at least one point in  $R_{pq}$ 

There is a separator  $(r_1, ..., r_{k-1})$  of S such that  $r_i \in R_{pq}$ 



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1) Compute a (\rho/2)-coreset \mathsf{K} \subseteq \mathsf{P} of size \mathsf{O}(1/\rho)
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2) Compute all antipodal pairs of the convex hull of *K*  $\triangleleft$  **Corollary.** There is an antipodal pair (p, q) of *K* such that  $p \in \sigma_1$  and  $q \in \sigma_k$ .





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# 4. Algorithm

1) Given a separator *R*, we can compute a minimum width *k*-slab cover of *P* respecting *R* in  $O(kn \log n)$  time and O(n) space.

2) We can compute  $O(\rho^{-k})$  candidate separators in  $O(n \log n + \rho^{-k})$  time.



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2) We can compute O(\rho^{-k}) candidate separators in O(n \log n + \rho^{-k}) time.
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**Theorem.** A minimum-width k-slab cover of P whose gap-ratio is at least  $\rho$  can be computed in  $O(\rho^{-k} \cdot kn \log n)$  time and O(n) space, if exists.



#### 4. Algorithm

# Thank you!

