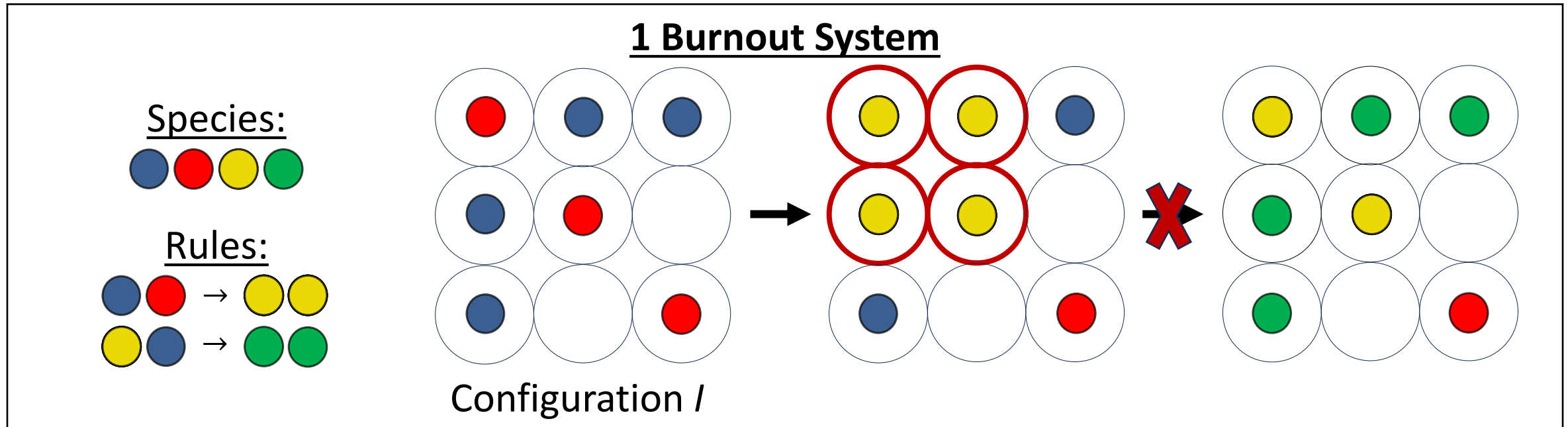


# Reconfiguration of Linear Surface Chemical Reaction Networks with Bounded State Change



Authors: Robert M. Alaniz, Michael Coulombe, Erik D. Demaine, Bin Fu, Timothy Gomez, Elise Grizzell, **Ryan Knobel**, Andrew Rodriguez, Robert Schweller, Tim Wylie

# Overview

1. Introduction to the Model
2. Motivation
3. Previous work/Contributions
  - Linear Surfaces
  - General Surfaces
  - Grid Surfaces
4. Conclusion

# Introduction to the Model

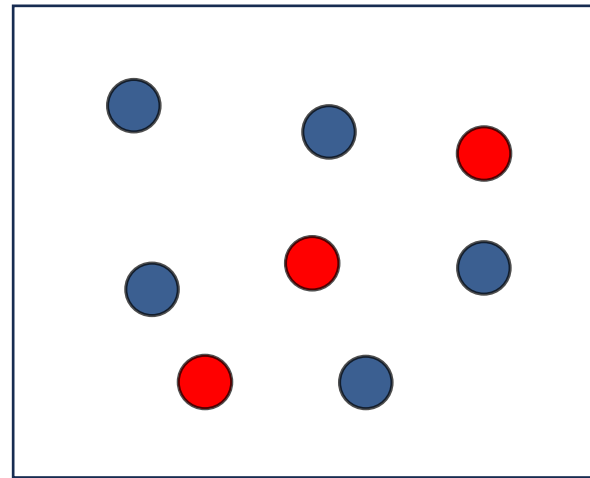
# Chemical Reaction Networks

- Ordered pair  $(\Lambda, \Gamma)$ 
  - $\Lambda$  = Set of input species
  - $\Gamma$  = Set of rules
- Configuration
  - Length  $|\Lambda|$  vector of non-negative integers
  - Represents count of each species

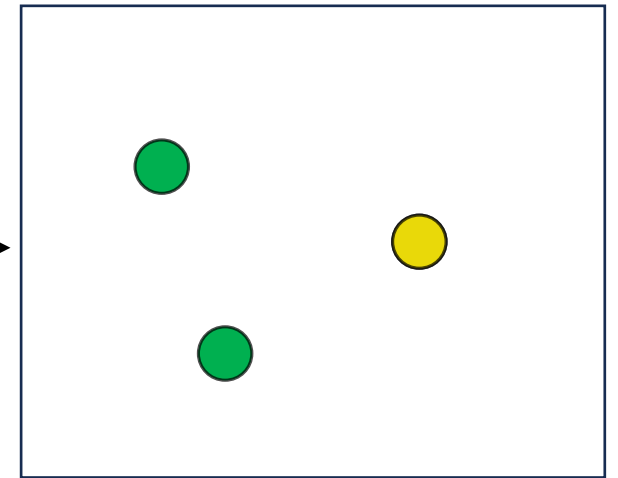
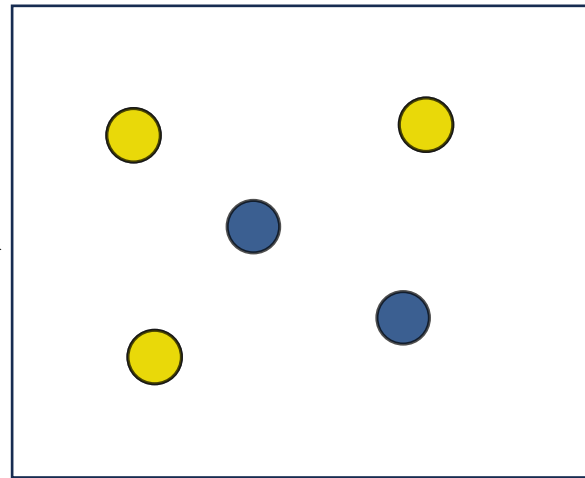
# Example CRN System

Species:  
● ● ● ●  
Blue Red Yellow Green

Rules:  
● ● → ●  
● ● → ●  
Blue Red → Yellow  
Yellow Blue → Green



Configuration I:  
[5, 3, 0, 0]

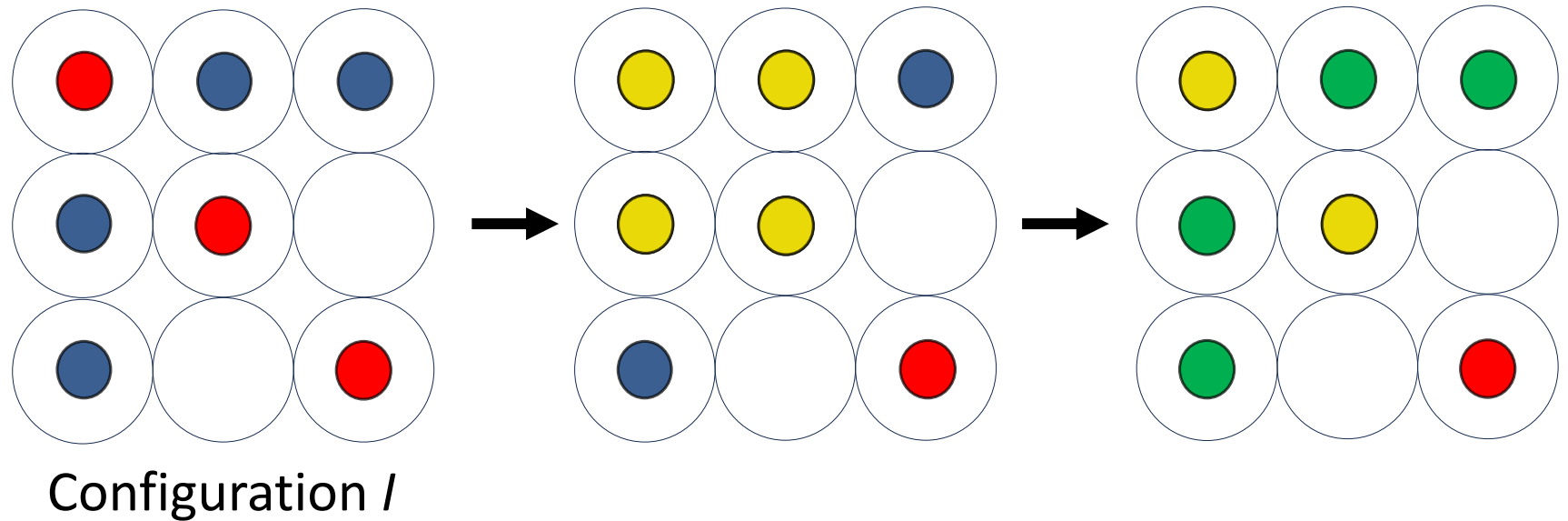
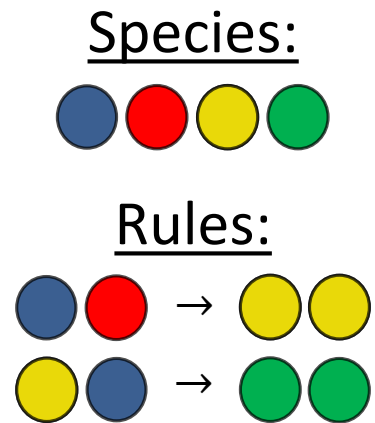


Configuration D:  
[0, 0, 1, 2]

# Surface Chemical Reaction Networks

- Ordered pair  $(\Lambda, \Gamma)$ 
  - $\Lambda$  = Set of input species
  - $\Gamma$  = Set of rules
- Surface
  - Undirected graph
- Configuration
  - Mapping of input species to vertices on the surface
  - Each vertex has no more than 1 species at a time

# Example sCRN System

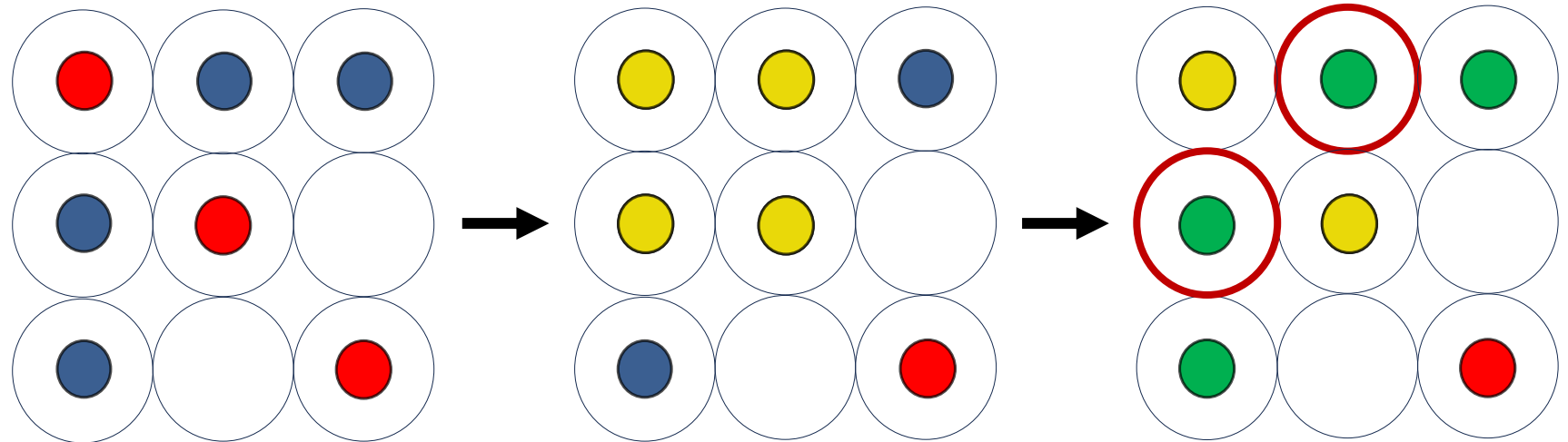
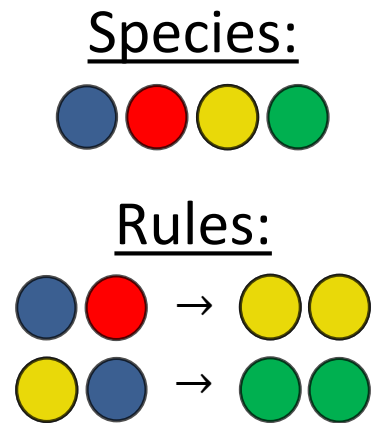


# Surface Chemical Reaction Networks

- Ordered pair  $(\Lambda, \Gamma)$ 
  - $\Lambda$  = Set of input species
  - $\Gamma$  = Set of rules
- Surface
  - Undirected graph
- Configuration
  - Mapping of input species to vertices on the surface
  - Each vertex has no more than 1 species at a time
- Burnout
  - Limit to how many times a vertex can change states

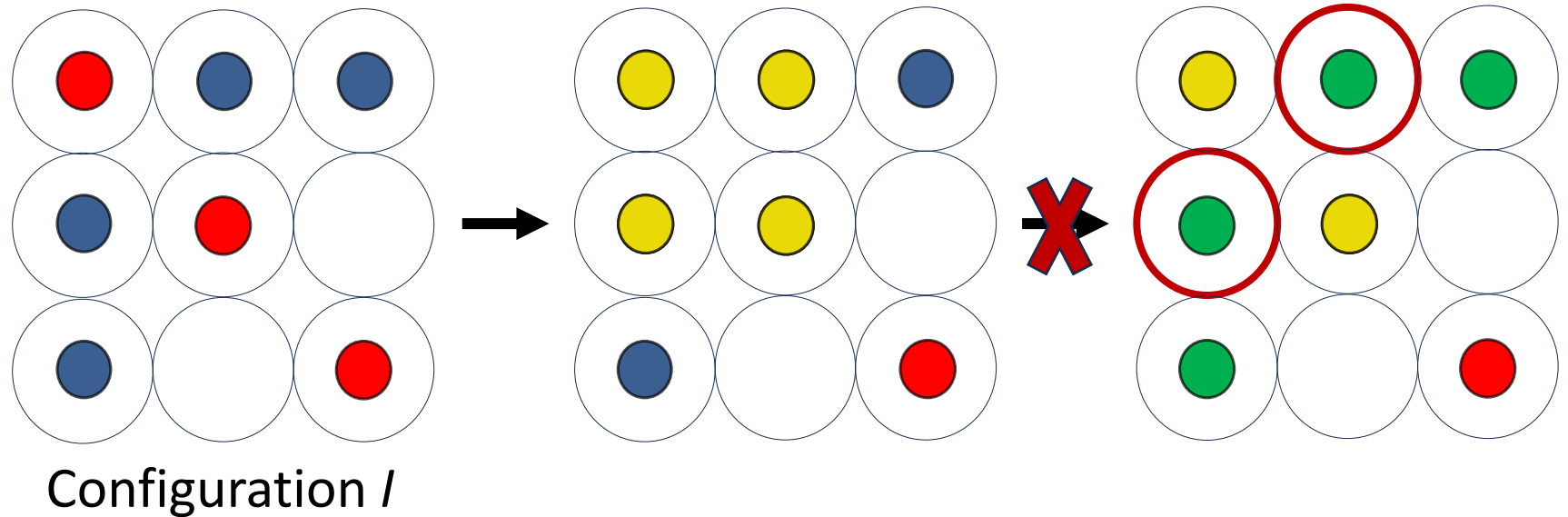
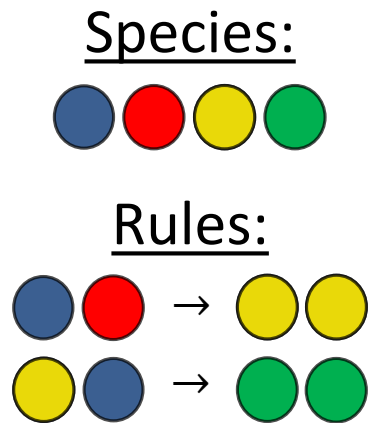


# Example sCRN System: 2 burnout

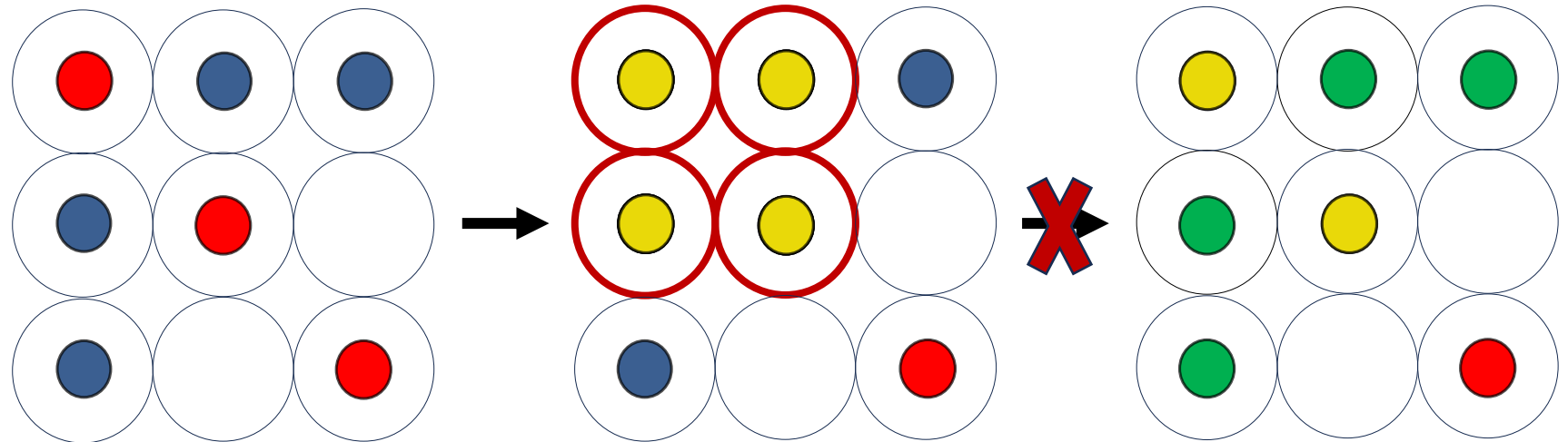
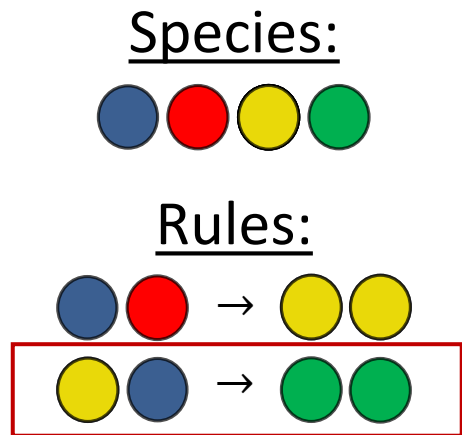


Configuration 1

# Example sCRN System: 1 burnout

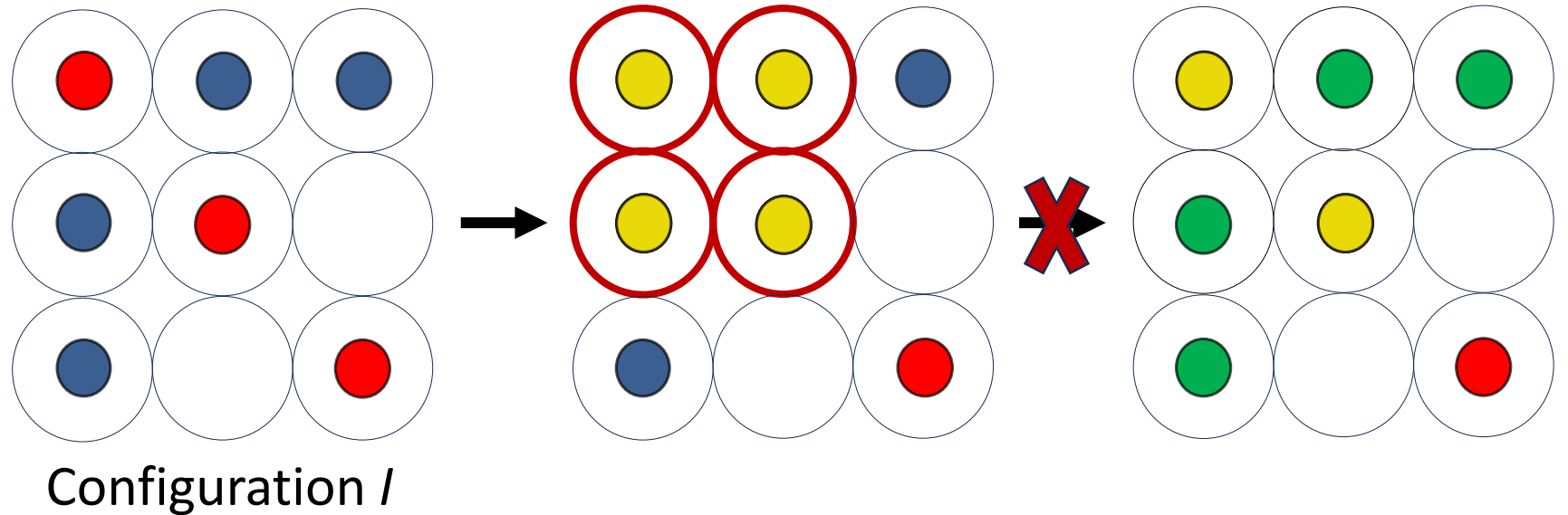
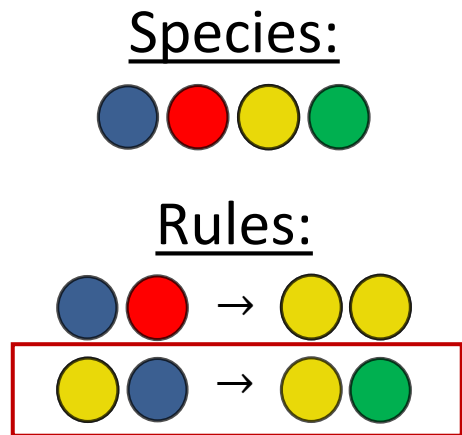


# Example sCRN System: 1 burnout

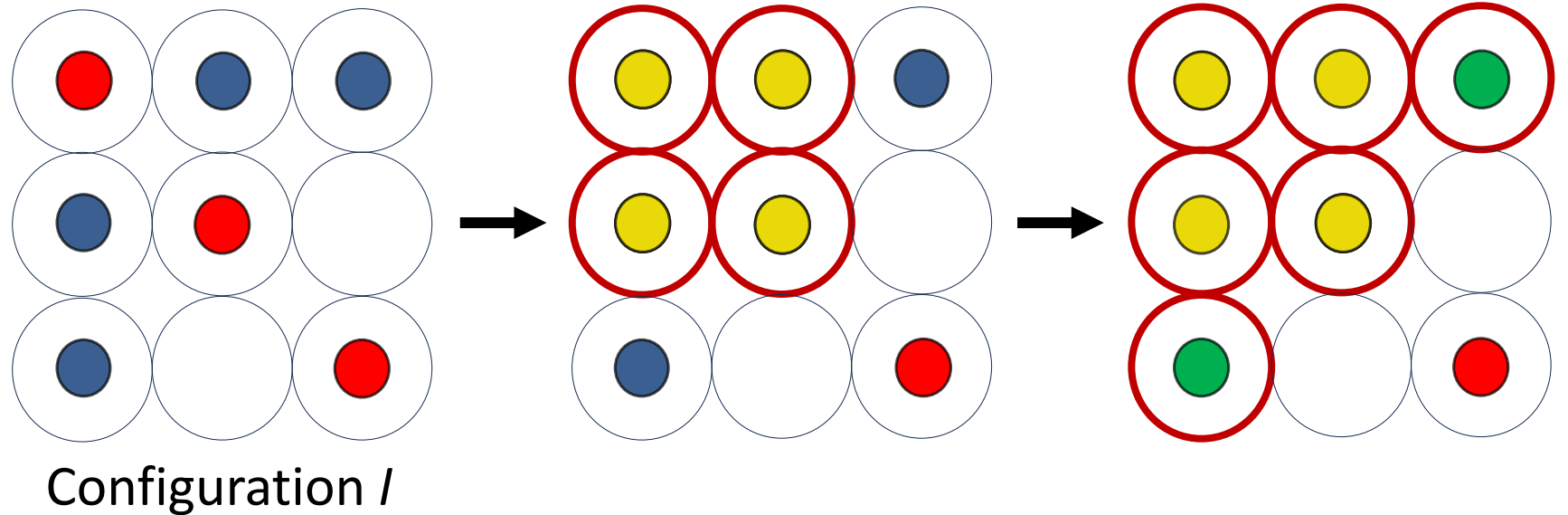
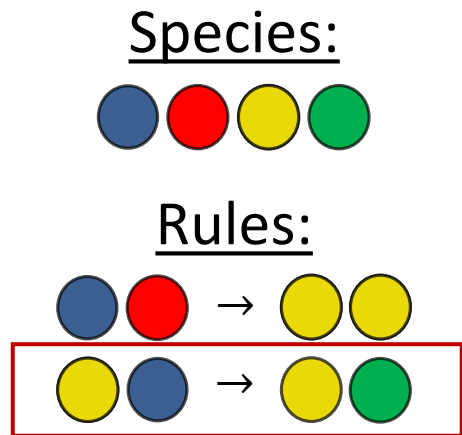


Configuration I

# Example sCRN System: 1 burnout

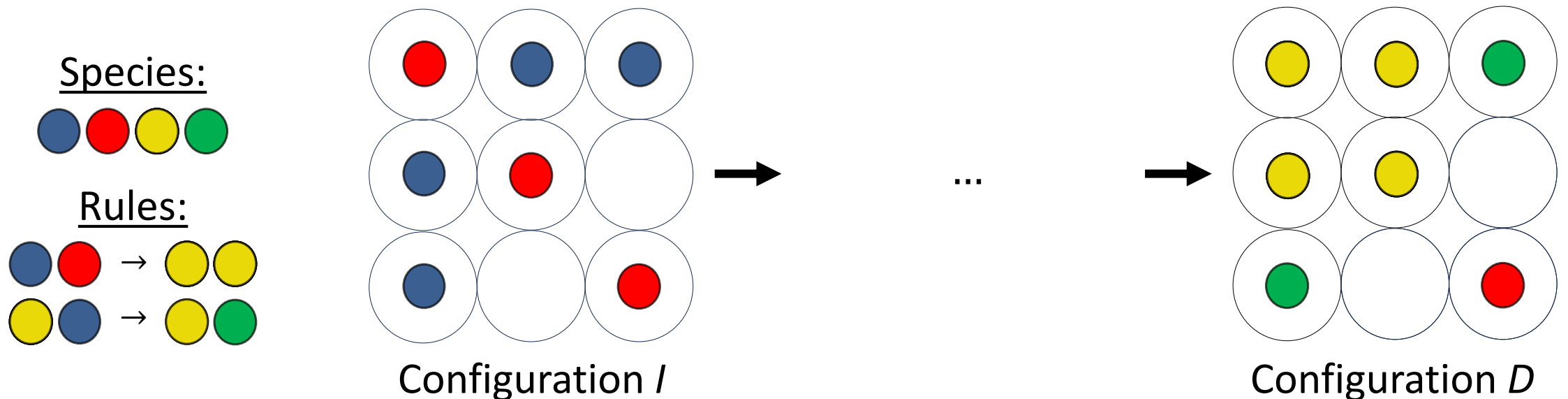


# Example sCRN System: 1 burnout



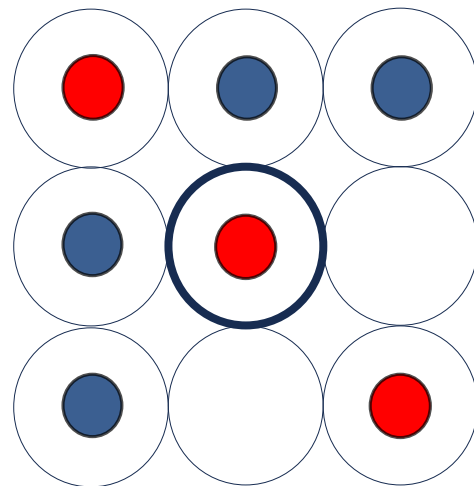
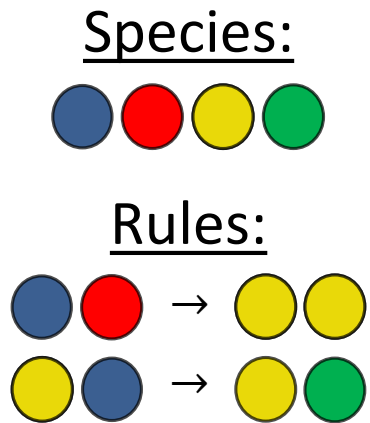
# Reconfiguration

- Given initial configuration  $I$  and target configuration  $D$ , can  $D$  ever be reached from  $I$ ?



# 1-Reconfiguration

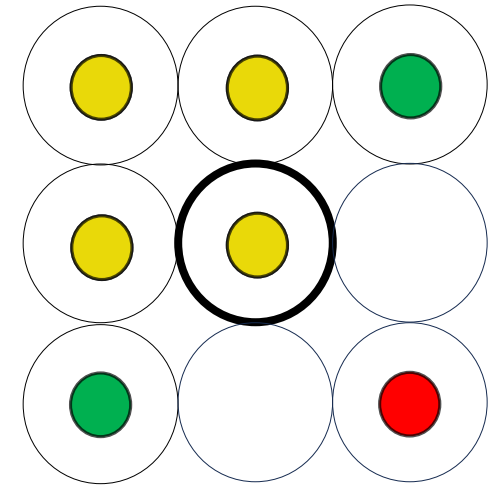
- Given initial configuration  $I$ , vertex  $v$  and species  $s$ , does  $s$  ever appear in  $v$ ?



Configuration  $I$



...



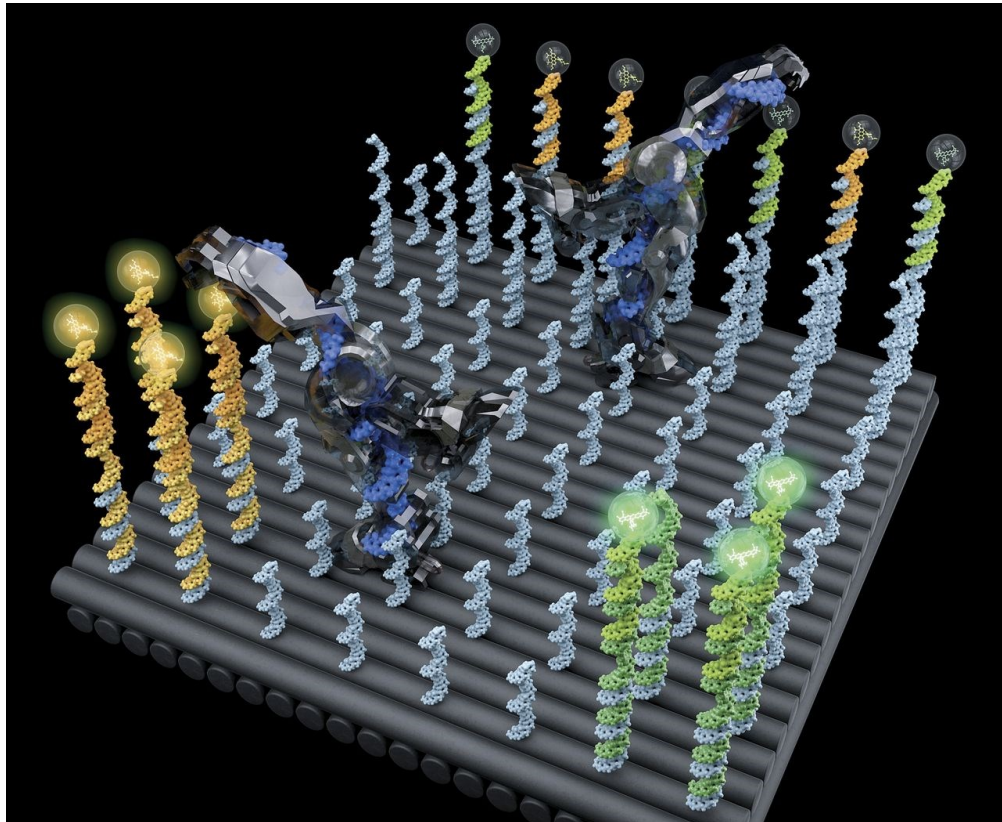
Motivation



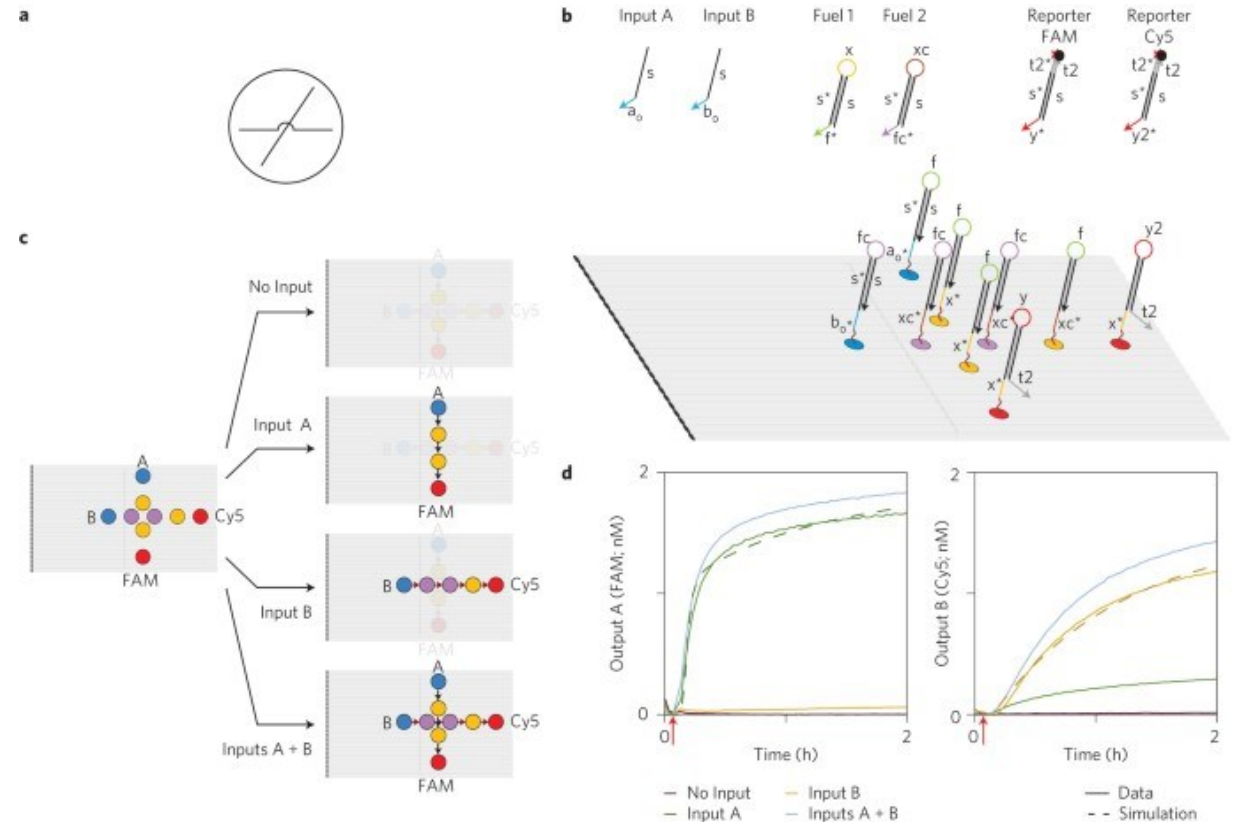
# Motivation

- CRNs are practical but limited in computational power
  - Deterministically compute semi-linear functions
- sCRNs help overcome some of these limitations
  - Some geometry
- Burnout reflects how molecules may interact
  - Molecules with limited lifetimes
  - Reactions that consume large quantities of energy

# Motivation



A. J. Thubagere, W. Li, R. F. Johnson, Z. Chen, S. Doroudi, Y. L. Lee, G. Izatt, S. Wittman, N. Srinivas, D. Woods, et al. **A cargo-sorting DNA robot.** *Science*, 357(6356):eaan6558, 2017.

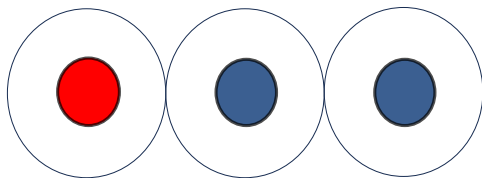


G. Chatterjee, N. Dalchau, R. A. Muscat, A. Phillips, and G. Seelig. **A spatially localized architecture for fast and modular DNA computing.** *Nature nanotechnology*, 12(9):920–927, 2017.

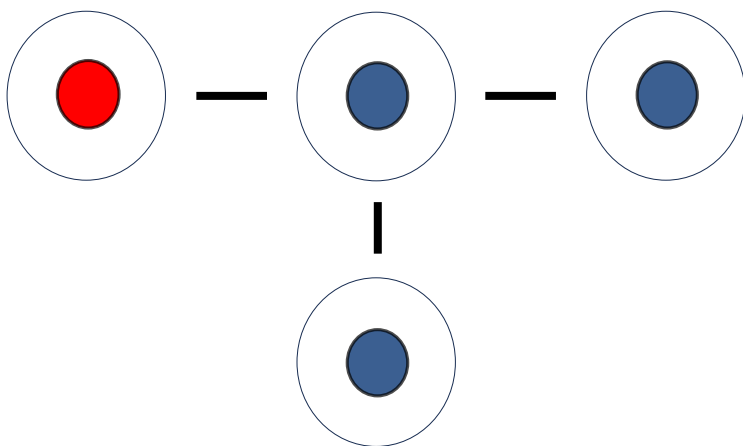
Previous work/Contributions

# Results

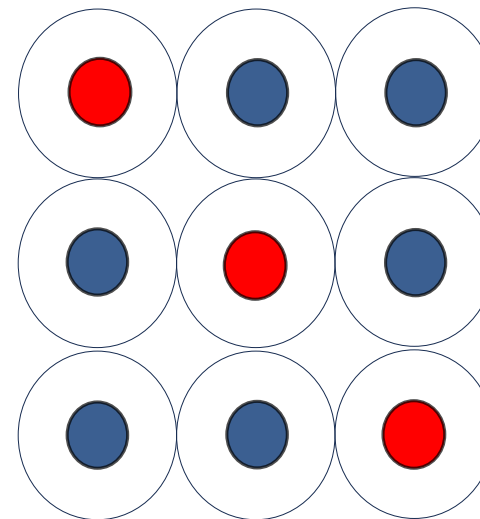
**Linear Surfaces**



**General Surfaces**



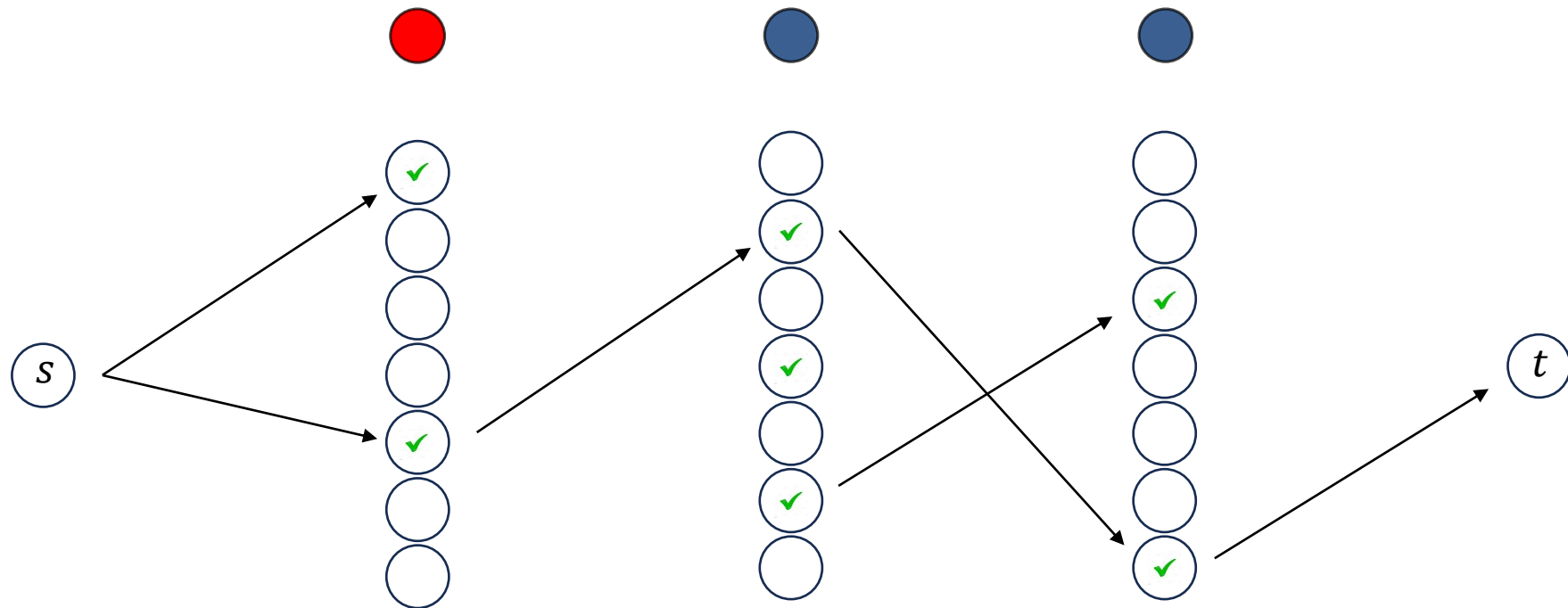
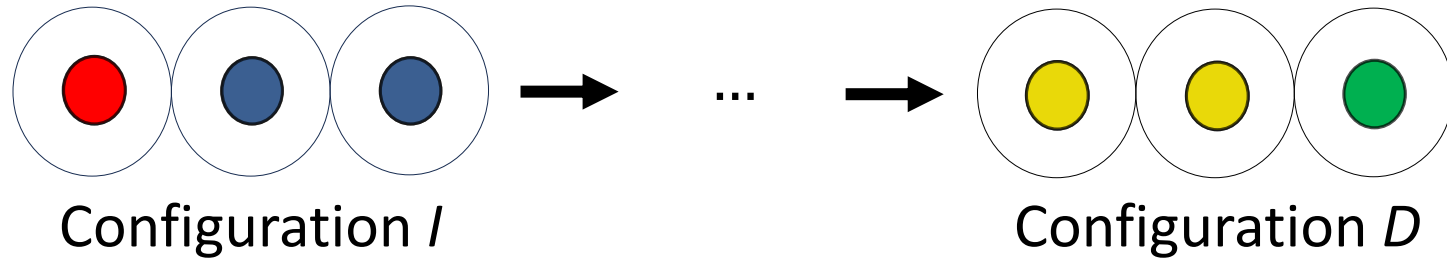
**Grid Surfaces**



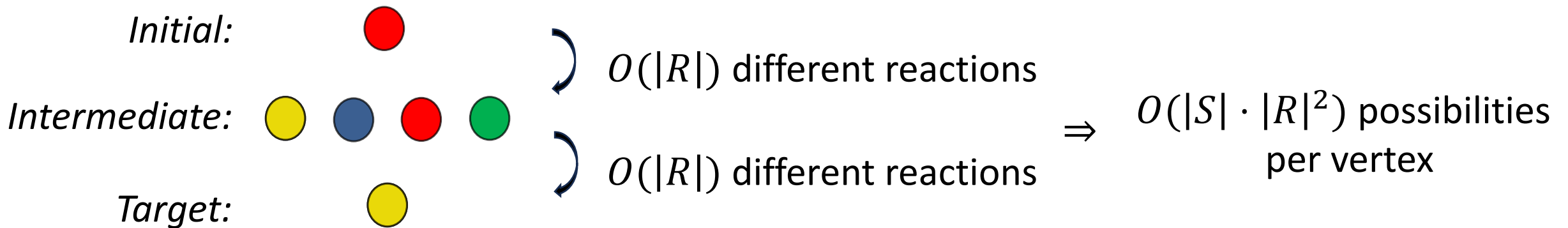
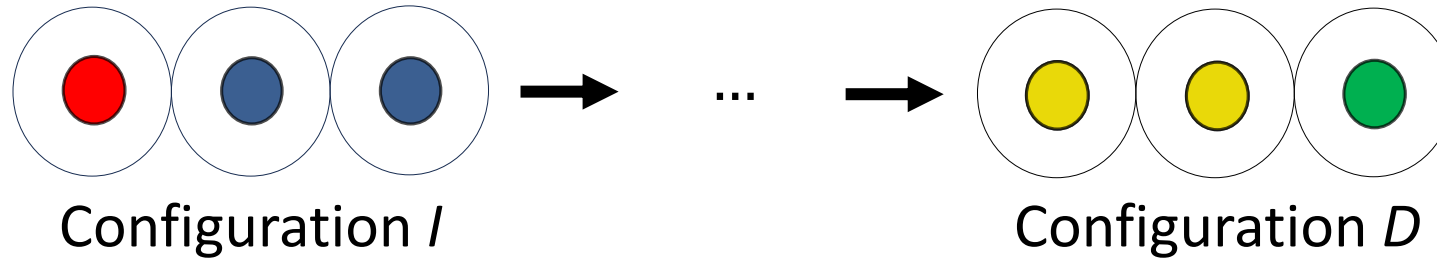
# Linear Surfaces

Problem	Burnout	Result
Reconfiguration	1	$O(n +  R )$
Reconfiguration	2	$O(n \cdot  S ^2 \cdot  R ^4)$
Reconfiguration	$O(1)$	P
Reconfiguration	$k$ (unary)	NP – Complete
Reconfiguration	None	PSPACE – Complete

# 1-burnout

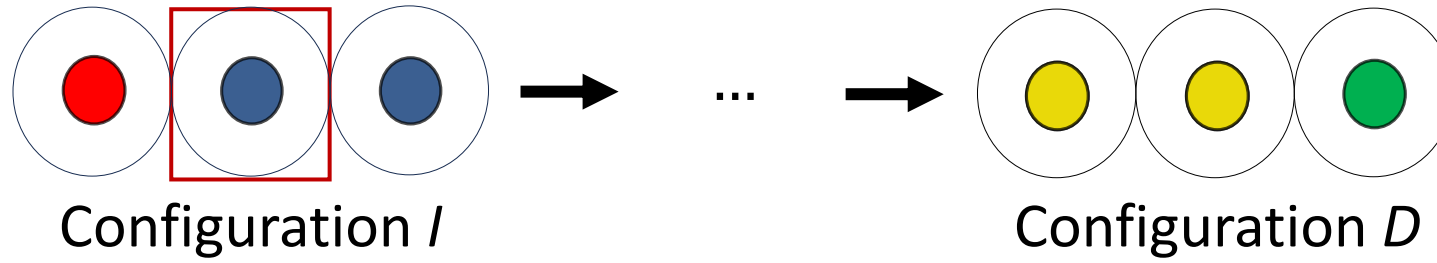


# 2-burnout



Result:  $O(n \cdot |S| \cdot |R|^2)$  cells and  $O(|S| \cdot |R|^2)$  runtime per cell =  $O(n \cdot |S|^2 \cdot |R|^4)$  runtime

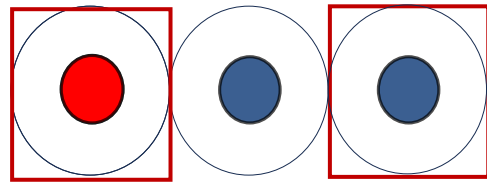
# $O(1)$ -burnout



$h^k$  combinations



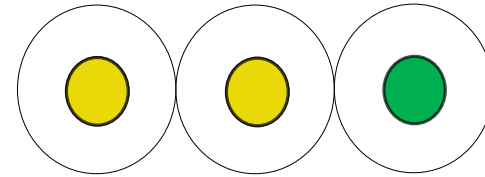
# $O(1)$ -burnout



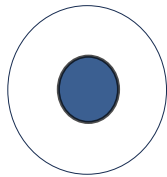
Configuration  $I$



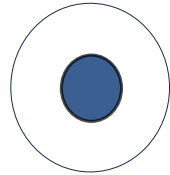
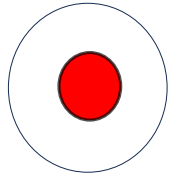
...



Configuration  $D$



$h^k$  combinations



$h^k$  combinations

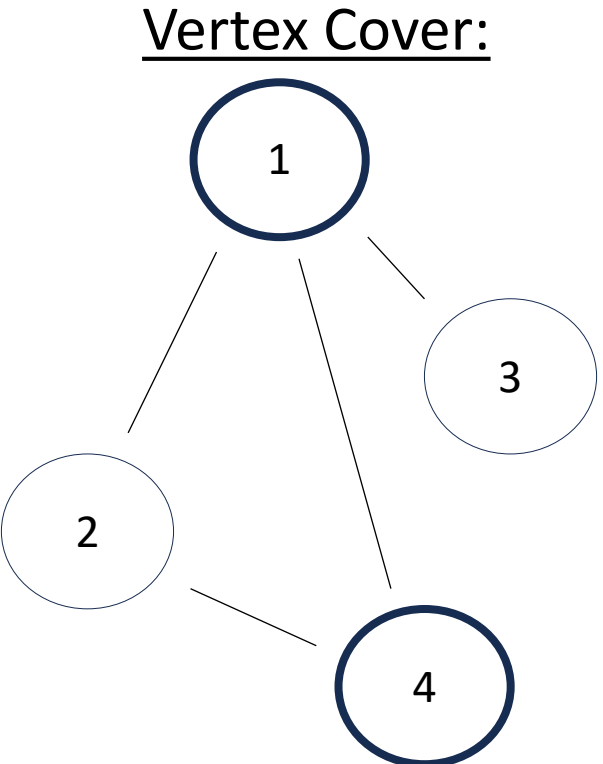
$h^k$  combinations



$$T(n) = h^k \left( 2 \cdot T\left(\frac{n}{2}\right) \right)$$

Result:  $O(h^{k \cdot \log(n)} * n)$  runtime, or  $O(n^{1+k \log(h)})$

# K-burnout



⇒

$$BS_0 - 12 - 13 - 14 - 24 - E$$



$$BS_0 - 1'x - 1'x - 1'x - x4' - E$$



$$B - xx - xx - xx - x4' - S_1^1 E$$



$$B - xx - xx - xx - x4' - S_1 E$$



$$BS_2^4 - xx - xx - xx - xx - E$$



$$BS_2 - xx - xx - xx - xx - E$$

⇒

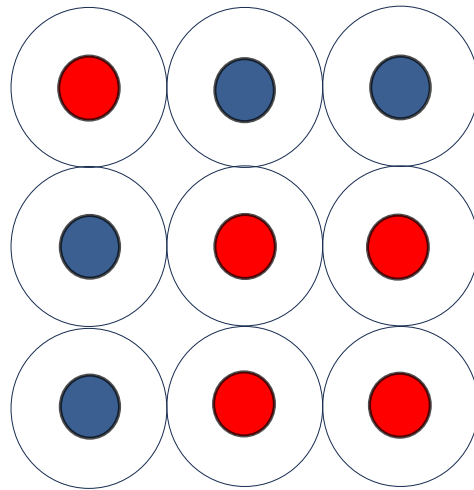
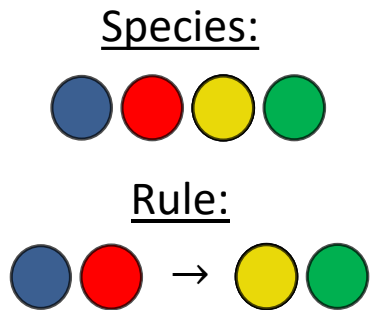
Vertex Cover of size  $k$  with  $k + 1$  burnout

# General Surfaces

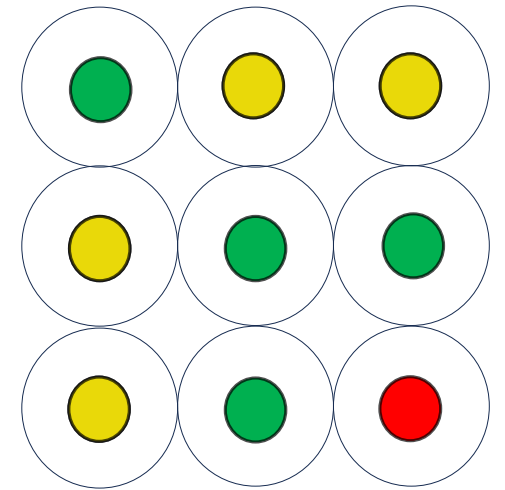
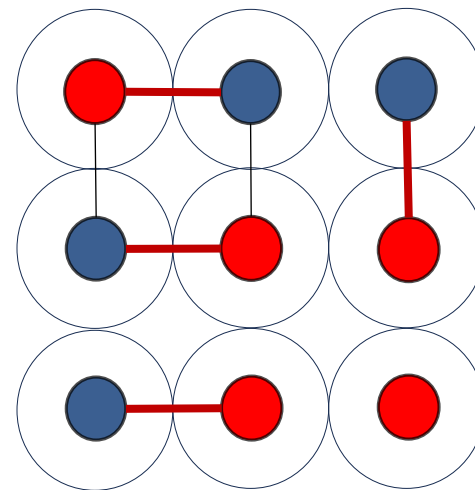
Problem	Burnout	Result
Reconfiguration	1	$O(V^{1.5} +  R )^*$
Reconfiguration	1	<i>NP – Complete</i>
Reconfiguration	2	<i>NP – Complete</i>

\* Non-catalytic reactions

# 1-burnout (Non-catalytic rules only)



Configuration *I*

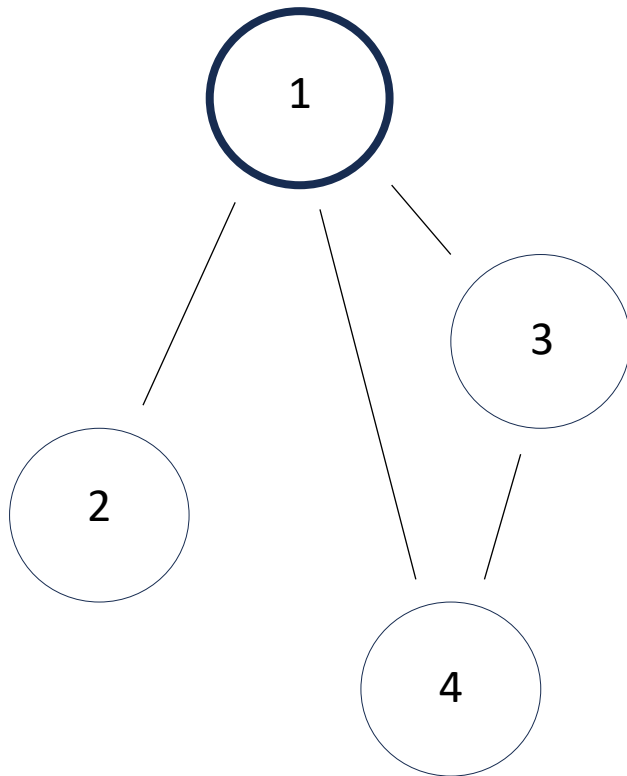


Configuration *D*

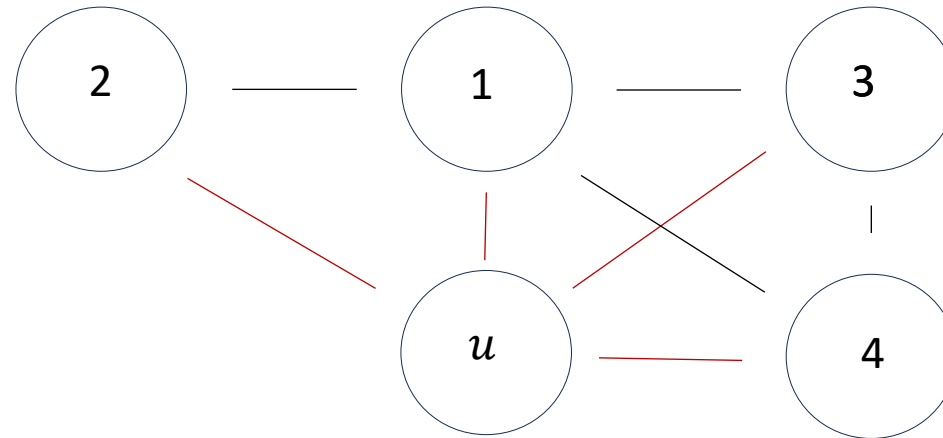
Planar:  $O(V^{1.5} + |R|)$   
General:  $O(V^4 + |R|)$

# 1-burnout (No restriction on rules)

Dominating Set:



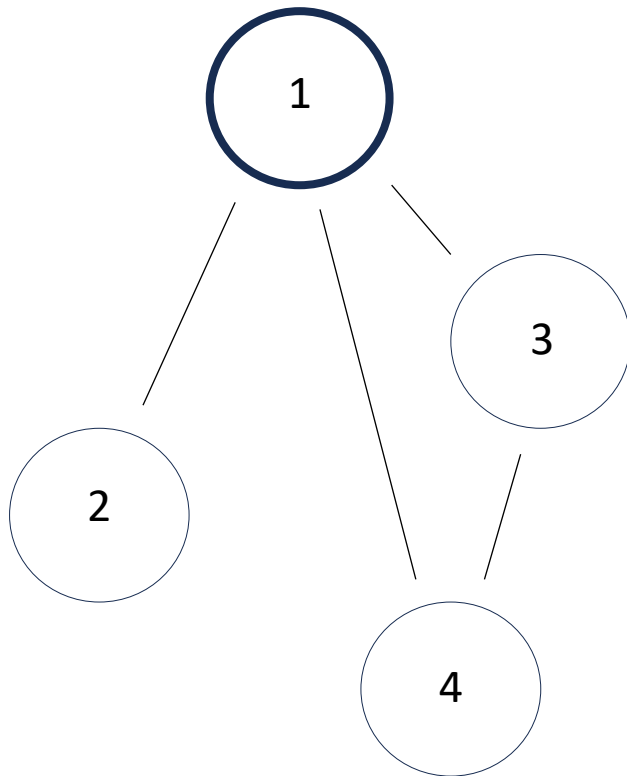
$\Rightarrow$



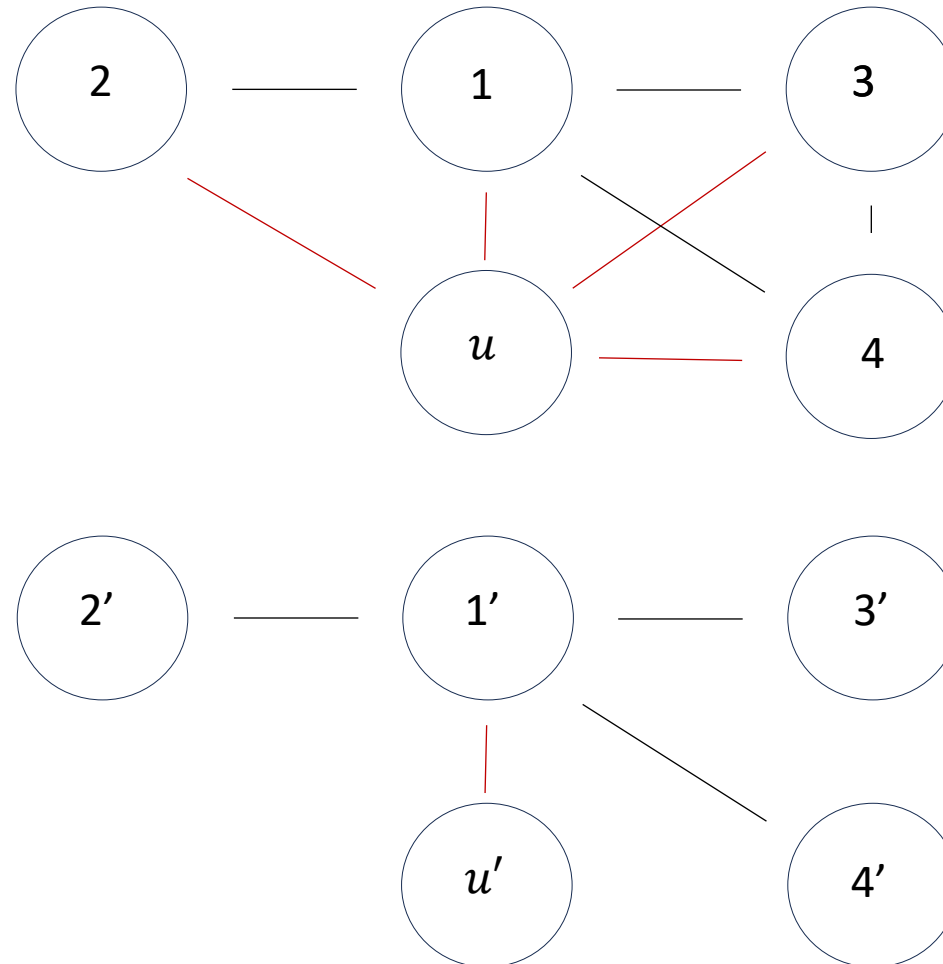
$$\begin{array}{ll} 1 + 2 \rightarrow 1' + 2 & u + 1 \rightarrow u' + 1' \\ 1 + 2 \rightarrow 1 + 2' & u + 2 \rightarrow u' + 2' \end{array}$$

# 1-burnout (No restriction on rules)

Dominating Set:



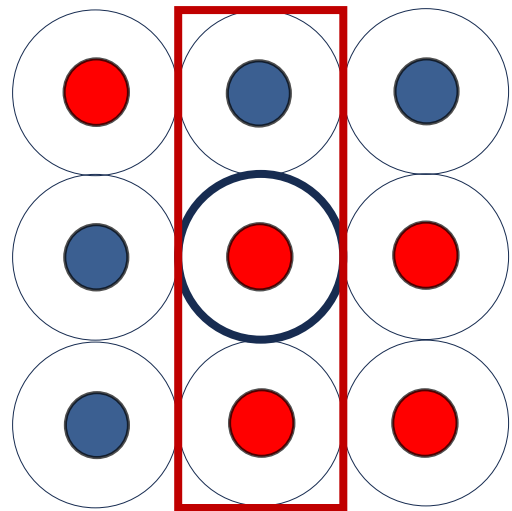
$\Rightarrow$



# Grid Surfaces

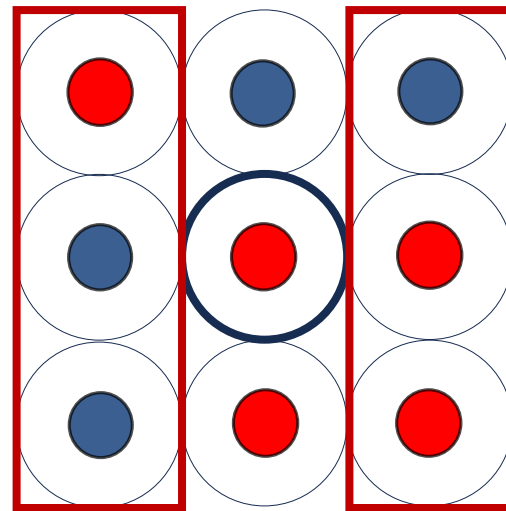
Problem	Burnout	Result
<b>1-Reconfiguration</b>	<b>1</b>	$O(n \cdot ( S  R )^{2m} \cdot f(m))$
1-Reconfiguration	1	<i>NP – Complete</i>

# 1-burnout (1-reconfiguration)



$O(|S|^m * (4|R|)^m * m!)$  cells

$\Rightarrow$



$\Rightarrow$

$O(|S|^m * (4|R|)^m * m!)$   
runtime per cell

Result:  $O(n \cdot (|S||R|)^{2m} \cdot f(m))$



Conclusion

# Known + New Results

## Linear Surfaces

Problem	Burnout	Result
Reconfiguration	1	$O(n +  R )$
Reconfiguration	2	$O(n \cdot  S ^2 \cdot  R ^4)$
Reconfiguration	$O(1)$	P
Reconfiguration	$k$ (unary)	<i>NP – Complete</i>
Reconfiguration	None	<i>PSPACE – Complete</i>

## General Surfaces

Problem	Burnout	Result
Reconfiguration	1	$O(V^{1.5} +  R )^*$
Reconfiguration	1	<i>NP – Complete</i>
Reconfiguration	2	<i>NP – Complete</i>

\* Non-catalytic reactions

## Grid Surfaces

Problem	Burnout	Result
1-Reconfiguration	1	$O(n \cdot ( S  R )^{2m} \cdot f(m))$
1-Reconfiguration	1	<i>NP – Complete</i>

# Open Problems

- Lower bounds for  $k$ -burnout on linear surfaces
- Other than size of surface, what about:
  - Species, rules and burnout
- Any FPT algorithms for reconfiguration

# Known + New Results

## Linear Surfaces

Problem	Burnout	Result
Reconfiguration	1	$O(n +  R )$
Reconfiguration	2	$O(n \cdot  S ^2 \cdot  R ^4)$
Reconfiguration	$O(1)$	P
Reconfiguration	$k$ (unary)	<i>NP – Complete</i>
Reconfiguration	None	<i>PSPACE – Complete</i>

## General Surfaces

Problem	Burnout	Result
Reconfiguration	1	$O(V^{1.5} +  R )^*$
Reconfiguration	1	<i>NP – Complete</i>
Reconfiguration	2	<i>NP – Complete</i>

\* Non-catalytic reactions

## Grid Surfaces

Problem	Burnout	Result
1-Reconfiguration	1	$O(n \cdot ( S  R )^{2m} \cdot f(m))$
1-Reconfiguration	1	<i>NP – Complete</i>