

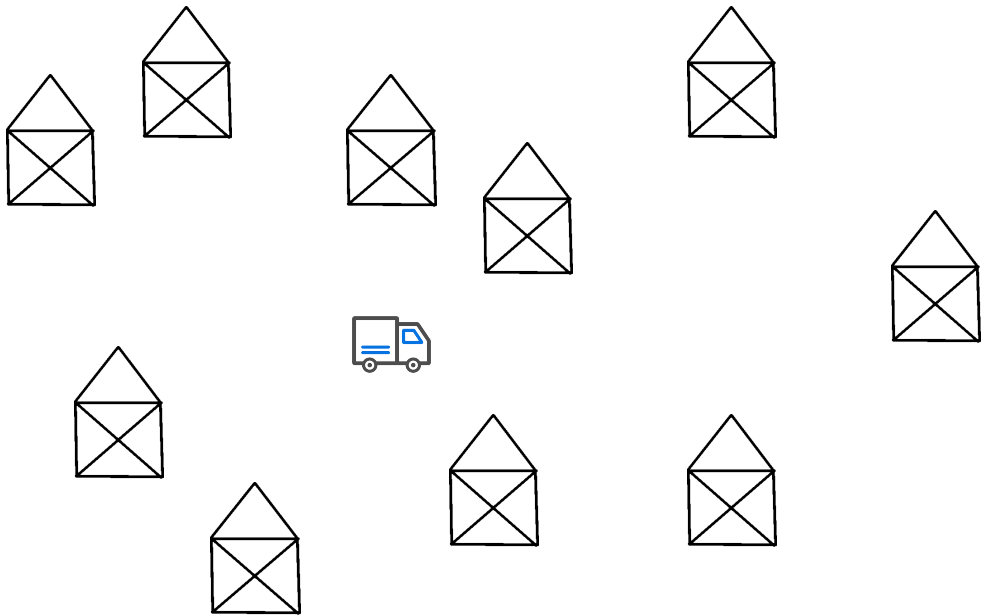
Online TSP with Known Locations

Evrpidis Bampis Bruno Escoffier Niklas Hahn **Michalis Xeferis**

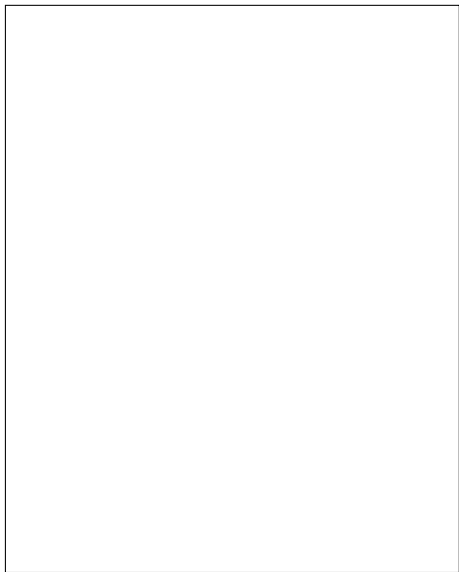
WADS 2023

31/07/2023

Traveling Salesperson Problem

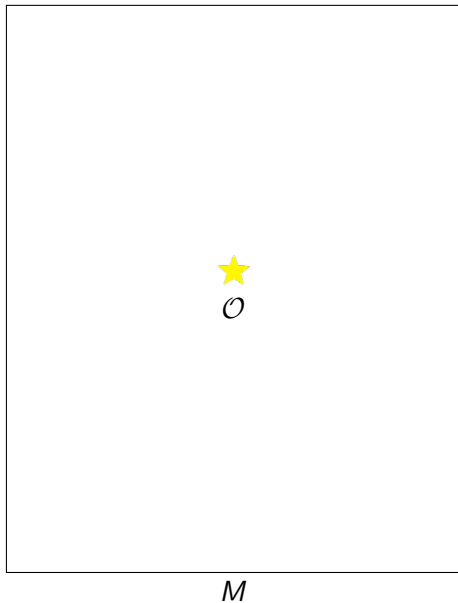


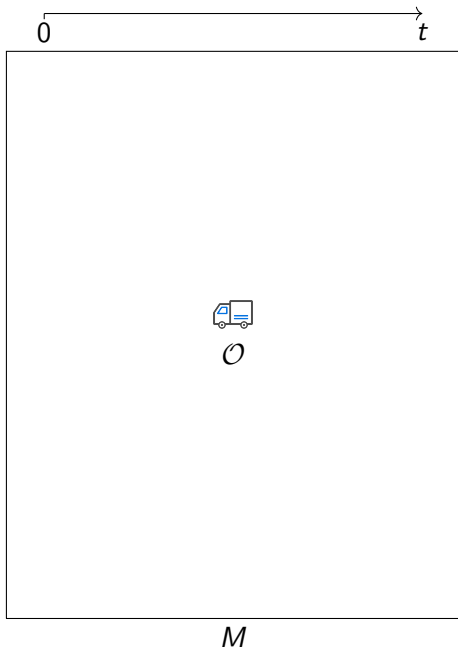
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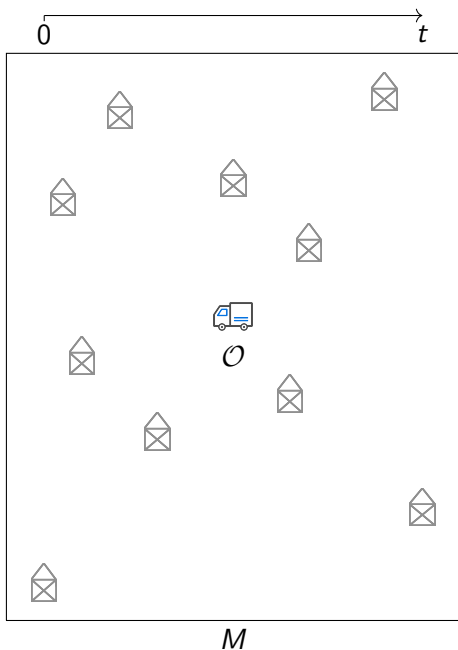
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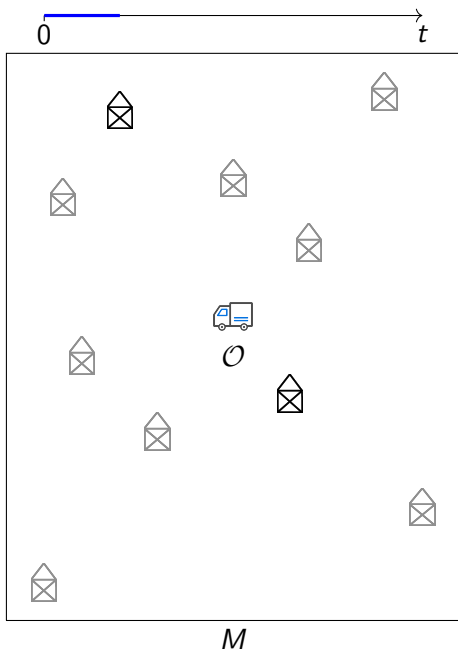




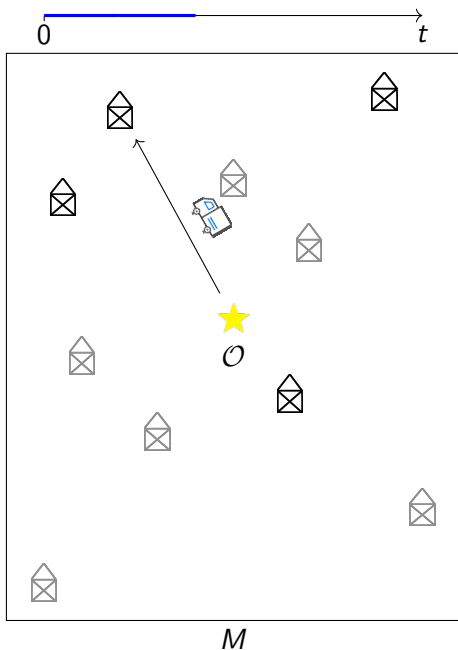
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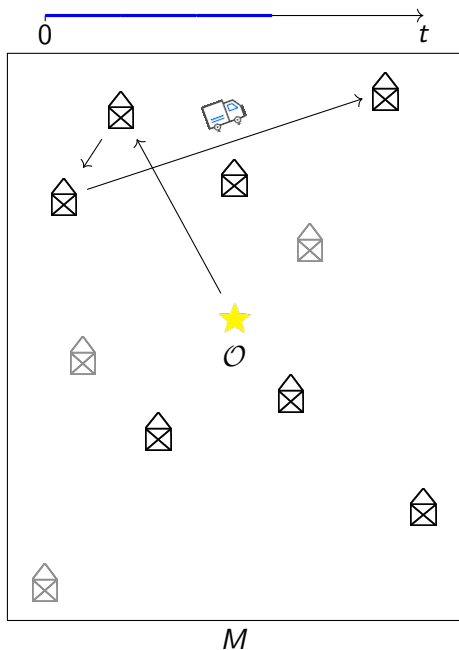
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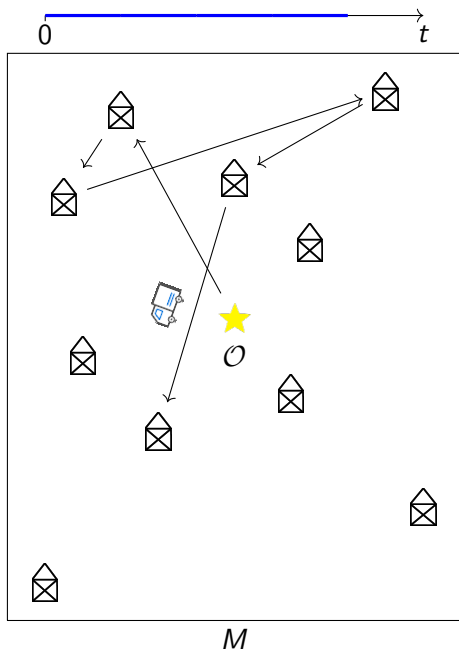
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- Objective: Minimize the completion time of the tour
- Open variant: \mathcal{S} finishes when reaching the final request
Closed variant: \mathcal{S} has to return to \mathcal{O}

Competitive Ratio

An **online** algorithm ALG has competitive ratio ρ if $|\text{ALG}(\sigma)| \leq \rho \cdot |\text{OPT}(\sigma)|$ for any input instance σ , where OPT is an optimal **offline** algorithm.

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Open variant, single request q with distance 1 and release time 1



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Classic Online TSP

Tight bound of 2 for the general case in the closed variant [Ausiello et al. '01]

Tight bound of 2.04 for the open variant on the line, 2.5 general upper bound

[Bjelde et al. '20, Ausiello et al. '01]

Observation

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Theorem

The algorithm for general metrics achieves a competitive ratio of $3/2$ in both the open and the closed variant of online TSP with known locations.

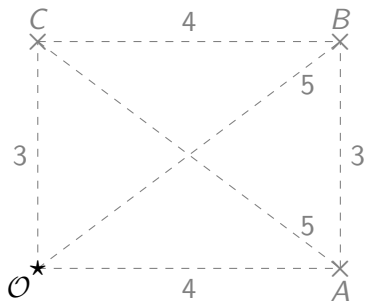
Main idea:

- Wait in \mathcal{O} until time t s.t. two conditions are satisfied for a single tour σ :
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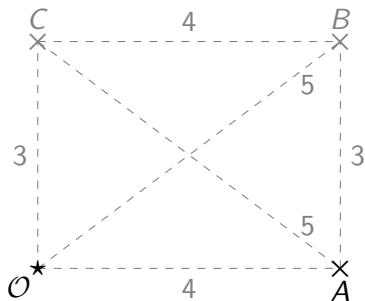
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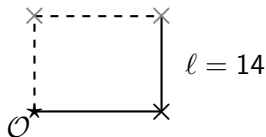
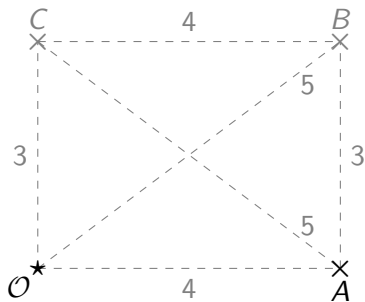
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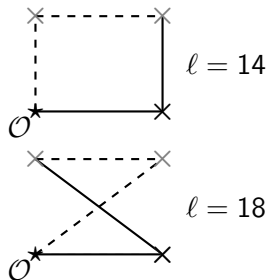
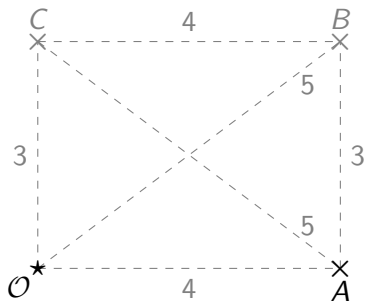
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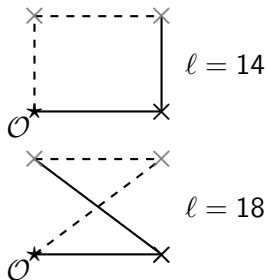
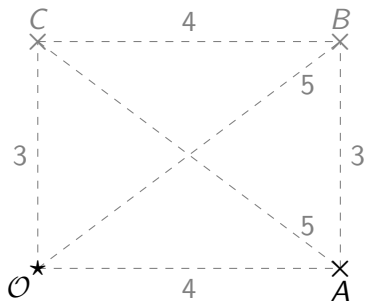
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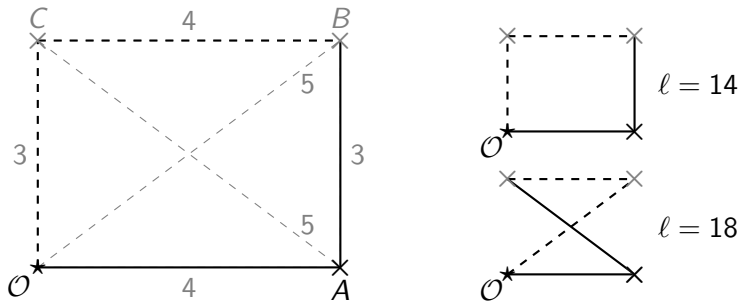
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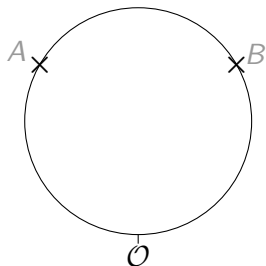
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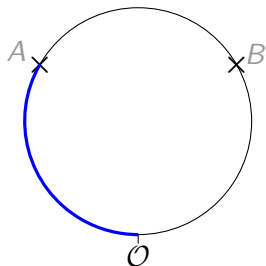
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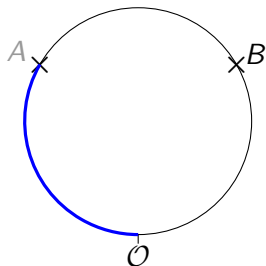


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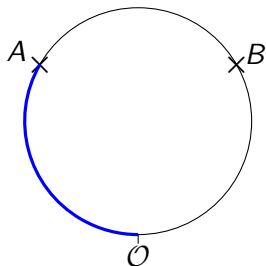
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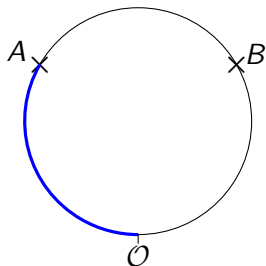
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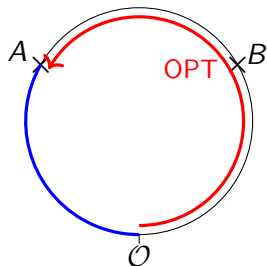
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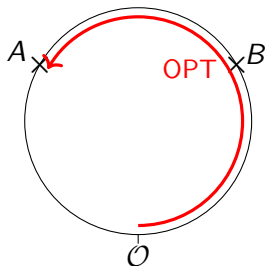
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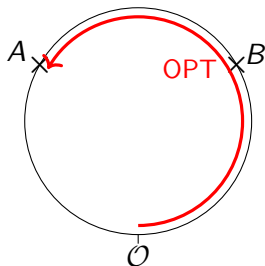
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[Gouleakis et al. '23]

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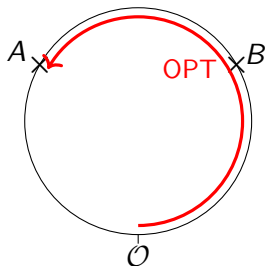
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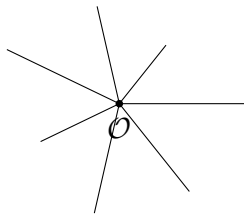
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\rightsquigarrow The general algorithm is optimal, **but** it is not poly-time

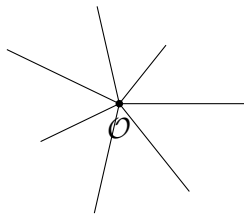
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Poly-time algorithm which is $(7/4 + \varepsilon)$ competitive (closed).



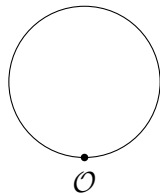
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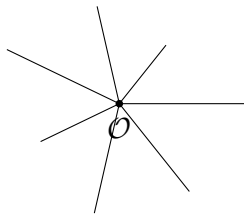
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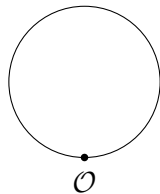
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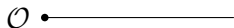
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Semi-line:

Poly-time algorithms which are 1 (closed) and $13/9$ competitive (open).



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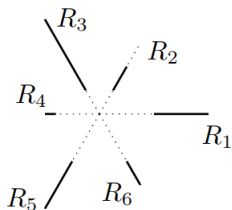
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 - Then, serve the requests in R and return to \mathcal{O} .
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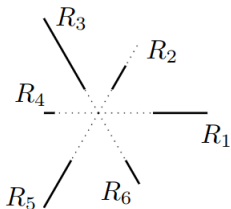
Example



Ray	R_1	R_2	R_3	R_4	R_5	R_6
Length	0.2	0.15	0.2	0.1	0.2	0.15
Released	0.1	0	0.15	0.02	0.1	0.05

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$\rightsquigarrow R$: rays R_1, R_3 and R_4 (or R_3, R_4, R_5) with a combined length of $1/2$ and released length of $\ell = 0.27$

	Open OLTSP-L		Closed OLTSP-L	
	Lower Bound	Upper Bound	Lower Bound	Upper Bound
Semi-line	$4/3$	$13/9^*$	1	1*
Star	$13/9$	$3/2$	$3/2$	$3/2$ $(7/4+\epsilon)^*$
Ring	$3/2$	$3/2$	$3/2$	$3/2$ $5/3^*$
General	$3/2$	$3/2$	$3/2$	$3/2$

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↪ Learning-Augmented
Online TSP on Rings, Trees,
Flowers and (almost) Every-
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Semi-line	$4/3$	$13/9^*$	1	1*
Star	$13/9$	$3/2$	$3/2$	$3/2$ $(7/4+\epsilon)^*$
Ring	$3/2$	$3/2$	$3/2$	$3/2$ $5/3^*$
General	$3/2$	$3/2$	$3/2$	$3/2$

Poly-time algorithms denoted by *

Open Questions

- Improving running time (general)
- Improving the Bounds
- Predictions on locations

↪ Learning-Augmented
Online TSP on Rings, Trees,
Flowers and (almost) Every-
where Else

Thank you!