# **External-Memory Sorting with Comparison Errors**

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# **Noisy Sorting Framework**

- Sort  $n$  distinct comparable elements
- Comparing two elements  $x$ ,  $y$  outputs true result independently according to a fixed probability  $p < 1/2$ , otherwise outputs false (opposite) result
- **Non-persistent** errors: determination of correctness made independently for each comparison
- **Persistent** errors: if previously compared pair of elements  $(x, y)$ , return that result instead



## **Noisy Sorting Framework: Motivation**

- A/B Testing
- Sport ranking





# **Noisy Sorting Framework: Evaluation**

- **Dislocation** of an element  $x$ : distance between current position and sorted position
- **Maximum dislocation** of an array
- **Total dislocation** of an array
- Worst-case of  $O(n)$  and  $O(n^2)$  respectively
- under persistent comparison errors

4



• Known lower bounds of  $\Omega(\log n)$  and  $\Omega(n)$  for best-possible max and total dislocation

# **Noisy Sorting Framework in External Memory**

- Goal: sort  $n$  items in external memory model using an optimal  $\Theta((N/B)\log_{M/B}(N/B))$ I/Os, while also being tolerant to noisy comparisons
- Interested in both cache-aware (parameters involve  $M$  and  $B$ ) and cache-oblivious settings



# **Noisy Sorting Framework in External Memory**

- Existing algorithms cannot be easily converted into an external memory algorithm
	- They make use of **noisy binary search**, which involves a random walk in a BST
	- Not cache efficient and takes 240  $\log n$  steps



## **Related Prior Work**





## **Preliminary: Window-Sort**

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- Takes  $O(d_1n)$  time in internal memory, and uses  $O((nd_1/B) + (\log(d_1/d_2))(n/B)\log_{M/B}(n/B))$  I/Os in external memory
- Allows us to achieve noise tolerance for our later algorithms

Algorithm 1: Window-Sort $(A = \{a_0, a_1, \ldots, a_{n-1}\}, d_1, d_2)$ 1 for  $w \leftarrow 2d_1, d_1, d_1/2, \ldots, 2d_2$  do foreach  $i \leftarrow 0, 1, 2, \ldots, n-1$  do 2

 $\left| \begin{array}{c} r_i \leftarrow \max\{0, i-w\} + |\{a_j < a_i : |j-i| \leq w\}|\end{array} \right|$ 

- 4 comparison key for  $a_i$ )
- $5$  return  $A$

3

• Takes as input an array of size  $n$  with max dislocation at most  $d_1 \leq n$  [Geissmann, Leucci, Liu, Penna (2019)] • Outputs array with max dislocation at most  $d_2/2$  w.h.p. as a function of  $d_2$  (typically choose  $d_2 = \Theta(\log n)$ )

Sort A (deterministically) by nondecreasing  $r_i$  values (i.e., using  $r_i$  as the

## **Window-Merge-Sort**

- Variant of merge sort that sorts with max dislocation  $O(\log n)$  under persistent errors, w.h.p
- Takes as input parameter  $d$ , the desired max dislocation, we choose  $d = c \log n$  for some constant  $c > 0$
- Not cache-oblivious, but sorts in external memory with optimal #I/Os, assuming  $B = \Omega(\log n)$
- We first consider an internal memory version that runs in  $O(n \log^2 n)$  time
- Given array A, split it into 2 subarrays  $A_1$ ,  $A_2$  of roughly equal size and recursively sort them
- Merge sublists by using Window-Sort as subroutine:
	- If  $|A_1| + |A_2| \le 6d$ , return Window-Sort $(A_1 \cup A_2, 4d, d)$



#### **Window-Merge-Sort: merge step**





#### **Window-Merge-Sort: merge step and key lemma**

while  $|A_1| + |A_2| > 6d$  do Let  $S_1$  be the first min $\{3d, |A_1|\}$  elements of  $A_1$ Let  $S_2$  be the first min $\{3d, |A_2|\}$  elements of  $A_2$ Let  $S \leftarrow S_1 \cup S_2$ Window-Sort $(S, 4d, d)$ Let  $B'$  be the first d elements of (the near-sorted) S

will result in a sequence with max dislocation at most  $3d/2$  w.h.p.

Proof: Omitted

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- Add  $B'$  to the end of B and remove the elements of  $B'$  from  $A_1$  and  $A_2$
- Lemma: If  $A_1$  and  $A_2$  each have max dislocation at most  $3d/2$ , then merging them

#### **External Window-Merge-Sort**

- Divide A into  $m = \Theta(M/B) \geq 2$  subarrays  $A_1, ..., A_m$  instead, each of roughly equal size
- For the merge step, bring in the first  $max\{3d, |A_i|\}$  elements from each  $A_i$  into a list S
- Call Window-Sort(S,  $4md$ ,  $d$ ). Since  $B = \Omega(\log n)$ , fits entirely in internal memory
- Output the first  $d$  elements from that call and repeat

will result in a sequence with max dislocation at most  $3d/2$  w.h.p.

Lemma: If  $A_1, ..., A_m$  each have max dislocation at most  $3d/2$ , then merging them

#### **External Window-Merge-Sort**

Theorem: Given an array A of  $n$  distinct comparable elements, one can deterministically sort A in  $O(n \log^2 n)$  time in internal memory or in external memory to have max dislocation at most  $O(\log n)$  w.h.p., assuming  $B \geq \log n$ .

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- with  $O((n/B)\log_{M/B}(n/B))$  I/Os subject to comparison errors with  $p \le 1/16$  so as
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### **Funnelsort and Cache-Obliviousness**

- Introduced by Frigo, Leiserson and Prokop in 1999
- performance (e.g. by loop tiling: breaking problem into optimally sized blocks for a given cache)
- cache, regardless of cache size
- Analysis: work complexity  $W(n)$ , cache complexity  $Q(n)$
- requires tall-cache assumption,  $M = \Omega(B^2)$

• Cache-Oblivious algorithms do not contain parameters dependent on M or B that can be tuned to optimize

• Such algorithms usually use divide-and-conquer: divide problem into smaller pieces until subproblem fits into

• Funnelsort: cache-oblivious sorting algorithm,  $W(n) = O(nlog n)$  and  $Q(n) = \Theta((N/B)log_{M/B}(N/B))$ ,



### **Preliminary: Funnelsort**

- Split input into  $n^{1/3}$  arrays of size  $n^{2/3}$ , sort them recursively
- Merge the  $n^{1/3}$  sorted sequences using a  $n^{1/3}$ -merger
- $k$ -merger: recursive data structure that merges  $k$  sorted sequences
- Idea: to achieve noise tolerance, use Window-Sort for base case  $k$ -mergers



Figure 4-1: Illustration of a k-merger. A k-merger is built recursively out of  $\sqrt{k}$  left  $\sqrt{k}$ mergers  $\mathcal{L}_1, \mathcal{L}_2, \ldots, \mathcal{L}_{\sqrt{k}}$ , a series of buffers, and one right  $\sqrt{k}$ -merger  $\mathcal{R}$ .

## **Constructing a k-merger**

- Invariant: one  $k$ -merger invocation outputs  $k^3$  elements of merged sequence
- To output  $k^3$  elements, R gets invoked  $k^{3/2}$ times
- Each left merger output connected to buffer of size  $2k^{3/2}$
- Before each invocation of R, if any buffer *i* has  $\lt k^{3/2}$  elements, invoke  $L_i$ once so that buffer has  $\geq k^{3/2}$  elements



**Figure 4-1:** Illustration of a k-merger. A k-merger is built recursively out of  $\sqrt{k}$  left  $\sqrt{k}$ mergers  $\mathcal{L}_1, \mathcal{L}_2, \ldots, \mathcal{L}_{\sqrt{k}}$ , a series of buffers, and one right  $\sqrt{k}$ -merger  $\mathcal{R}$ .



### **Window-Funnelsort**

- Cache-oblivious, but requires  $B = \Omega(\log n)$  in addition to tall-cache assumption
- $n^{1/3}$ -merger
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- $\langle$  clogn for constant  $c > 0$
- k-mergers with  $k > c \log n$  work the same (recursive) way as original Funnelsort

• Same general structure as Funnelsort: recursively sort  $n^{1/3}$  sequences of size  $n^{2/3}$ , feed into

• Modify  $k$ -merger construction such that base-case merges are done using Window-Merge

• Original Funnelsort: base case at  $k=2$ , Window-Funnelsort: base cases  $\sqrt{c \log n} \leq k$ 



### **Window-Funnelsort**

- We prove that Window-Funnelsort:
	- has optimal cache complexity  $Q(n) = O((N/B)\log_{M/B}(N/B))$
	- has work complexity  $W(n) = O(n\log^2 n)$
	- sorts with optimal maximum dislocation  $O(logn)$  under persistent errors, w.h.p.
- We provide a proof sketch for  $Q(n)$ , and omit the remaining two proofs for this talk

## **Cache complexity of a** *k***-merger**

merger with  $\sqrt{c \log n} \le k \le \alpha \sqrt{M}$  will fit entirely in the cache

 $\Rightarrow$   $O(k + k^3/B)$  cache misses for reading/writing  $k^3$  elements

Lemma: One invocation of a k-merger incurs  $O(k + k^3/B + k^3 \log_M k/B)$  cache misses.

- Proof sketch: From the previous lemma, and assuming  $B = \Omega(\log n)$  and  $M = \Omega(B^2)$ , any  $k$ -
- In this case, since  $B = O(\sqrt{M})$ , there are at least  $M/B = \Omega(k)$  blocks available for buffers
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- We incur an additional  $O(k^2/B)$  cache misses due to the  $O(k^2)$  space used by k-merger

## **Cache complexity of a** *k***-merger**

at most  $2k^{3/2} + 2\sqrt{k}$  times

which incurs at most  $\sqrt{k}$  misses and is repeated  $k^{3/2}$  times

We have  $Q_k \leq (2k^{3/2} + 2\sqrt{k})Q_{\sqrt{k}} + k^2$ , which has solution  $Q_k \leq O(k^3 \log_M k / B)$ 

#### Lemma: One invocation of a k-merger incurs  $O(k + k^3/B + k^3 \log_M k/B)$  cache misses.

Proof sketch (cont.): For k-mergers with  $k > \alpha \sqrt{M}$ , we invoke the internal  $\sqrt{k}$ -mergers a total of

The  $k$ -merger also needs to check before each invocation of  $R$  whether any buffers are empty,



### **Cache complexity of Window-Funnelsort**

misses.

Proof sketch: We have  $Q(n) = n^{1/3}Q(n^{2/3}) + Q_{n^{1/3}}$ , where  $Q_{n^{1/3}}$  is # of cache misses of  $n^{1/3}$ -merger

From the previous lemma we know that  $Q_{n^{1/3}} = 0$ 

So we get  $Q(n) = n^{1/3}Q(n^{2/3}) + O(n \log_M n / B)$ , which has solution  $Q(n) = O((N/B)\log_{M/B}(N/B))$ 

#### Theorem: Window-Funnelsort incurs at most  $Q(n) = O((N/B)\log_{M/B}(N/B))$  cache

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m(n^{1/3} + n/B + n\log_M n/B)
$$



### **Conclusions/Future work**

- setting (cache-aware and cache-oblivious)
- Improvements can be made for total dislocation and work complexity
- Can we do without the assumption that  $B = \Omega(\log n)$ ?
- Can other cache-oblivious algorithms be made noise-tolerant? (e.g. cache-oblivious distribution sort)

• We provided cache-optimal and noise tolerant sorting algorithms in the external memory

Our work (cache-oblivious and cache-aware)  $O(n \log^2 n)$   $O(\log n)$   $O(n \log n)$   $O((N/B) \log_{M/B}(N/B))$ Time Max Disloc. Total Disloc. I/Os

